

Sampling via Nonlinear Diffusion Equations

Women in OT Workshop

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Motivation

Setup: Let μ be a probability measure on Euclidean space \mathbb{R}^d .

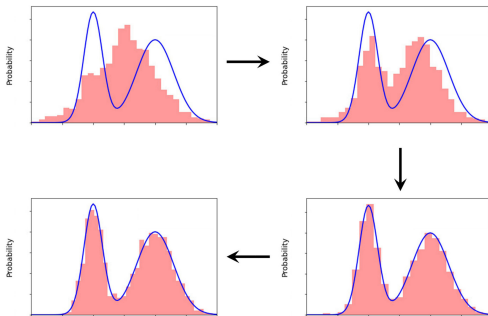
Goal: We seek $f: \mathbb{R}^d \rightarrow \mathbb{R}$ such that the empirical measure $\frac{1}{n} \sum_{i=1}^n \delta_{x_i}$ converges to μ as $n \rightarrow \infty$.

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- Our definition of “convergence” depends on the context of the problem. For example, we may define convergence in terms of the 2-Wasserstein metric.



Source: Science Direct, 2021

Classical Approach: Langevin Dynamics

Assumption: The target measure $\tilde{\mu}$ is strongly log-concave, i.e. $\tilde{\mu} = e^{-V(x)} dx$ for a μ -convex function $V : \mathbb{R}^d \rightarrow \mathbb{R}$, $\mu > 0$.

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For any initialization $x_{j,0} \in \mathbb{R}^d$, evolving particles by the stochastic differential equation

$$\begin{cases} dx_j(t) = -\gamma \log(\tilde{\nu}(x_j)) dt + dW_j \\ x_j(0) = x_{j,0} \end{cases}$$

ensures that $\lim_{t \rightarrow \infty} \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n x_i(t) = \tilde{\nu}$.

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Remark (Continuum Perspective)

At time t , the particles approximate $(t; x)$, the solution to the **Fokker-Planck equation**:

$$\begin{cases} \partial_t (t; x) + \gamma \operatorname{div} (x \log(\tilde{\cdot}(x))) = 0 \\ (0; x) = \delta_0(x) \end{cases}$$

$(t; x)$ converges to $\tilde{\cdot}$ as $t \rightarrow \infty$.

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A new approach allows us to consider target measures of the form

$$\tilde{\mu} = ((f^\theta)^{-1}(Z - V(x)))_+ dx;$$

where

- Z is a normalizing constant.
- $V : \mathbb{R}^d \rightarrow \mathbb{R}$ and $f : [0; 1] \rightarrow \mathbb{R}$ are smooth.
- V is λ -convex for some $\lambda > 0$.
- f is convex and $s \mapsto s^d f(s^{-d})$ is convex and nonincreasing on $(0; 1)$.

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Key idea: If $(t; x)$ is a solution to the **Generalized Fokker-Planck equation**:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \nabla V) = \operatorname{div}(\rho f^0(\cdot)) & t > 0 \\ \rho(0; x) = \rho_0(x); \end{cases}$$

then $(t; x)$ still converges to $\tilde{\mu}$ as $t \rightarrow \infty$.

Sampling via Nonlinear Diffusion Equations

Goal: Develop a stochastic particle method to approximate $(t; x)$, the solution to the Generalized Fokker-Planck equation.

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Preliminary results:

Trouble case:

References

- Craig, Katy, Karthik Elamvazhuthi, Matt Haberland, and Olga Turanova. “A blob method for inhomogeneous diffusion with applications to multi-agent control and sampling.” *Mathematics of Computation* (2023).
- Craig, Katy, Matt Jacobs, and Olga Turanova. “A blob method for general nonlinear diffusion.” In preparation.
- Jin, Shi, Lei Li, and Jian-Guo Liu. “Random batch methods (RBM) for interacting particle systems.” *Journal of Computational Physics* (2020).

A Particle Method for Generalized Fokker-Planck Equation

For simplicity, assume that f is of the form

$$f(x) = \begin{cases} \frac{x^m}{m-1} & m > 1 \\ x \log(x) & m = 1 \end{cases}$$

This function is associated with the diffusion equation.
Then our particles flow according to the following ODE:

$$\begin{aligned} \dot{x}_i(t) &= -r V(x_i(t)) + \sum_{k=1}^{\mathbb{P}} (r'(x_k - x_j) m_k)^{m-2} + \sum_{k=1}^{\mathbb{P}} (r'(x_i - x_k) m_k)^{m-2} \\ &\quad - \sum_{j=1}^{\mathbb{P}} (r'(x_j - x_i) m_j) \end{aligned}$$

$$x_i(0) = x_i^0$$

Here, $f m_i g_{i=1}^n$ are defined by $m_i = \frac{\phi(x_i)}{n^d}$. ϕ is a mollifier.